

# Static Flexural Analysis of Thick Isotropic Beam Using Hyperbolic Shear Deformation Theory

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**Abstract**-Flat slabs are highly versatile elements widely used in construction, providing minimum depth, fast construction and allowing flexible column grids. Common practice of design and In the present study, a hyperbolic shear deformation theory is developed for static flexural analysis of thick isotropic beams. The theory assumes a parabolic variation of transverse shear stress across the thickness of the beams. Simply supported thick isotropic beams analysed for the axial displacement, Transverse displacement, Axial bending stress and transverse shear stress. In this theory the hyperbolic sine and cosine function is used in the displacement field to represent the shear deformation effect and satisfy the zero transverse shear stress condition at top and bottom surface of the beams. The Governing differential equation and boundary conditions of the theory are obtained by using Principle of virtual work. The simply supported isotropic beam subjected to varying load is examined using present theory. The numerical results have been computed for various lengths to thickness ratios of the beams and the results obtained are compared with those of Elementary, Timoshenko, Trigonometric and other higher order refined theories and with the available solution in the literature

**Keywords:**

**Thick beam, shear deformation, isotropic beam, transverse shear stress, static flexure, hyperbolic shear deformation theory, principle of virtual work**

The wide spread use of shear flexible materials in air craft, automotive, shipbuilding and other industries has stimulated interest in the accurate prediction of structural behaviour of beams. Theories of beams involve basically the reduction of a three dimensional problems of elasticity theory to a one-dimensional problems. Since the thickness dimension is much smaller than the longitudinal dimension, it is possible to approximate the distribution of the displacement, strain and stress components in the thickness dimension. The various methods of development of refined theories based on the reduction of the three dimensional problems of mechanics of elastic bodies are discussed by Goldenveizer [1], Kilechvskiy [2], Donnell [3], Vlasov and Leontev [4], Sayir and Mitropoulos [5].

It is well-known that elementary theory of bending of beam based on Euler-Bernoulli hypothesis that the plane sections which are perpendicular to the neutral layer before bending remain plane and perpendicular to the neutral layer after bending, implying that the transverse shear and transverse normal strains

are zero. Thus the theory disregards the effects of the shear deformation. It is also known as classical beam theory. The theory is applicable to slender beams and should not be applied to thick or deep beams. When elementary theory of beam (ETB) is used for the analysis thick beams, deflections are underestimated and natural frequencies and buckling loads are overestimated. This is the consequence of neglecting transverse shear deformations in ETB. Rankine [6], Bresse [7] were the first to include both the rotatory inertia and shear flexibility effects as refined dynamical effects in beam theory. This theory is, however, referred to as the Timoshenko beam theory as mentioned in the literature by Rebello, et al. [8] and based upon kinematics it is known as first-order shear deformation theory (FSDT). Rayleigh [9] included the rotator inertia effect while later the effect of shear stiffness was added by Timoshenko [10]. Timoshenko showed that the effect of shear is much greater than that of rotatory inertia for transverse vibration of prismatic beams. In Timoshenko beam theory transverse shear strain distribution is constant through the beam thickness and therefore requires shear correction factor to correct the strain energy of deformation. Cowper [11] and Murty [13] have given new expressions for this coefficient for different cross-sections of the beam. Stephen and Levinson [15] have introduced a refined theory incorporating shear curvature, transverse direct stress and rotatory inertia effects. The limitations of the elementary theory of bending (ETB) of beams and first order shear deformation theory (FSDT) for beams forced the development of higher order shear deformation theories Soler [16] developed the higher order theory for thick isotropic rectangular elastic beams using Legendre polynomials and Tsai and Soler [17] extended it to orthotropic beams. Effects of shear deformation and transverse normal stress are included. Levinson [18] obtained the higher order beam theory providing the fourth order system of differential equations, satisfying two boundary conditions at each end of the beam. No shear correction factors are required since the theory satisfies the shear stress free surface conditions on the top and bottom of the beam. Krishna Murty [22] formulated a third order beam theory including the transverse shear strain and non classical (nonlinear) axial stress. In this theory the parabolic transverse shear stress distribution across the depth of the beam can be obtained using constitutive relations. Ghugal and Dahake [23] has developed a trigonometric shear deformation theory for flexure of thick or deep beams, taking into account transverse shear deformation effect. The number of variables in the present theory is same as that in the

First order shear deformation theory. The sinusoidal function is used in displacement field in terms of thickness coordinate to represent the shear deformation effects. This theory obviates the need of shear correction factor. Ghugal and Sharma [26], Sayyad and Ghugal [28] developed a variationally consistent refined hyperbolic shear deformation theory for flexure and free vibration of thick isotropic beam. This theory takes into account transverse shear deformation effects. In this paper, a hyperbolic shear deformation theory is developed for static flexural analysis of thick isotropic beams. The theory is applied to a Simply supported thick isotropic beams to analysed the axial displacement, Transverse displacement, Axial bending stress and transverse shear stress. The numerical results obtained for various lengths to thickness ratios of the beams and the results obtained are compared with those of Elementary, Timoshenko, Trigonometric and other higher order refined theories and with the available solution in the literature.

## 2. Formulation of Problem

Consider a thick isotropic simply supported beam of length  $L$  in  $x$  direction, Width  $b$  in  $y$  direction and depth  $h$  as shown in Figure 1. Where  $x, y, z$  are Cartesian coordinates. The beam is subjected to transverse load of intensity  $q(x)$  per unit length of beam. Under this condition, the axial displacement, Transverse displacement, Axial bending stress and transverse shear stress are required to be determined.

### 2.2 Assumptions made in the theoretical formulation:

1. The axial displacement ( $u$ ) consist of two parts:
  - (a) Displacement given by elementary theory of bending.
  - (b) Displacement due to shear deformation, which is assumed to be hyperbolic in nature with respect to thickness coordinate.
2. The transverse displacement ( $w$ ) in  $z$  direction is assumed to be function of  $x$  coordinate.
3. One dimensional constitutive laws are used.
4. The beam is subjected to lateral load only.

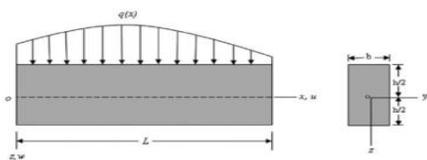


Figure 1: Simply supported beam bending under  $x$ - $z$  Plane

### 2.3 The Displacement Field:

Based on the above mentioned assumptions, the displacement field of the present beam theory can be expressed as follows. The hyperbolic function is assigned according to the shearing stress distribution through the thickness of beam.

Where

$$u(x, z, t) = -z \frac{\partial w}{\partial x}(x, t) + \left[ h \sinh\left(\frac{z}{h}\right) - \frac{4z^3}{3h^2} \cosh\left(\frac{1}{2}\right) \right] \phi(x, t) \quad \text{Axial} \quad (1)$$

$$w(x, t) = w(x, t) \quad (2)$$

displacement in  $x$  direction which is function of  $x, z$  and  $t$ .  
 $w$  = Transverse displacement in  $z$  direction which is function of  $x$  and  $t$ .  
 $\phi$  = Rotation of cross section of beam at neutral axis

due to shear which is an unknown function to be determined and it is a function of  $x$  and  $t$ .

Normal strain:

$$\epsilon_x = \frac{\partial u}{\partial x} = -z \frac{\partial^2 w}{\partial x^2} + \left[ h \sinh\left(\frac{z}{h}\right) - \frac{4z^3}{3h^2} \cosh\left(\frac{1}{2}\right) \right] \frac{\partial \phi}{\partial x} \quad (3)$$

Shear Strain

$$\gamma_{xz} = \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} = \left[ \cosh\left(\frac{z}{h}\right) - 4\frac{z^2}{h^2} \cosh\left(\frac{1}{2}\right) \right] \phi \quad (4)$$

Stresses:

The one dimensional Hooke's law is applied for isotropic material, stress  $\sigma_x$  is related to strain  $\epsilon_x$  and shear stress is related to shear strain by the following constitutive relations.

$$\sigma_x = E \epsilon_x = -zE \frac{\partial^2 w}{\partial x^2} + E \left[ h \sinh\left(\frac{z}{h}\right) - \frac{4z^3}{3h^2} \cosh\left(\frac{1}{2}\right) \right] \frac{\partial \phi}{\partial x} \quad (5)$$

$$\tau_{xz} = G \gamma_{xz} = G \left[ \cosh\left(\frac{z}{h}\right) - 4\frac{z^2}{h^2} \cosh\left(\frac{1}{2}\right) \right] \phi \quad (6)$$

where  $E$  and  $G$  are the elastic constants of the beam material.

### 2.4 Governing differential equations:

Governing differential equations and boundary conditions are obtained from Principle of virtual work. Using equations for stresses, strains and principle of virtual work, variationally consistent differential equations for beam under consideration are obtained. The principle of virtual work when applied to beam leads to:

$$\begin{aligned}
 & b \int_{x=0}^{x=L} \int_{z=-h/2}^{z=h/2} (\sigma_x \cdot \delta \epsilon_x + \tau_{xz} \cdot \delta \gamma_{xz}) dx dz \\
 & + \rho b \int_{x=0}^{x=L} \int_{z=-h/2}^{z=h/2} \left( \frac{\partial^2 u}{\partial t^2} \cdot \delta u + \frac{\partial^2 w}{\partial t^2} \cdot \delta w \right) dx dz \\
 & - \int_{x=0}^{x=L} q \delta w dx = 0
 \end{aligned} \tag{7}$$

Employing Greens theorem in above Equation successively, we obtain the coupled Euler-Lagrange equations which are the governing differential equations and associated boundary conditions of the beam. The governing differential equations obtained are as follows:

$$\begin{aligned}
 EI \left[ \frac{\partial^4 w}{\partial x^4} - A_0 \frac{\partial^3 \phi}{\partial x^3} \right] - \rho I \left[ \frac{\partial^4 w}{\partial x^2 \partial t^2} - A_0 \frac{\partial^3 \phi}{\partial x \partial t^2} \right] \\
 + \rho A \frac{\partial^2 w}{\partial t^2} = q(x, t)
 \end{aligned} \tag{8}$$

$$\begin{aligned}
 EI \left[ A_0 \frac{\partial^3 w}{\partial x^3} - B_0 \frac{\partial^2 \phi}{\partial x^2} \right] - \rho I \left[ A_0 \frac{\partial^3 w}{\partial x \partial t^2} - B_0 \frac{\partial^2 \phi}{\partial t^2} \right] \\
 + GAC_0 \phi = 0
 \end{aligned} \tag{9}$$

Where  $A^0$ ,  $B^0$  and  $C^0$  are the stiffness coefficients in governing equations. The associated consistent natural boundary conditions obtained are of following form along the edges  $x = 0$  and  $x = L$ .

$$EI \left[ \frac{\partial^3 w}{\partial x^3} - A_0 \frac{\partial^2 \phi}{\partial x^2} \right] - \rho I \left[ \frac{\partial^3 w}{\partial x \partial t^2} - A_0 \frac{\partial^2 \phi}{\partial t^2} \right] = 0 \tag{10}$$

Where  $w$  is Prescribed.

$$EI \left[ \frac{\partial^2 w}{\partial x^2} - A_0 \frac{\partial \phi}{\partial x} \right] = 0 \tag{11}$$

Where  $\frac{\partial w}{\partial x}$  is Prescribed.

$$EI \left[ A_0 \frac{\partial^2 w}{\partial x^2} - B_0 \frac{\partial \phi}{\partial x} \right] = 0 \tag{12}$$

Where  $\phi$  is Prescribed.

The flexural behaviour of beam is given by solution of above equations 8 and 9 by discarding all terms containing time derivatives and satisfying the associate boundary conditions. The stiffness coefficient used in governing equations Equations 8,9,10,11 and 12 are described as below:

$$A_0 = \left[ 12 \cosh \left( \frac{1}{2} \right) - 24 \sinh \left( \frac{1}{2} \right) - \frac{1}{5} \cosh \left( \frac{1}{2} \right) \right] \tag{13}$$

$$\begin{aligned}
 B_0 = 6 [\sinh(1) - 1] - 200 \cosh^2 \left( \frac{1}{2} \right) \\
 + 432 \sinh \left( \frac{1}{2} \right) \cosh \left( \frac{1}{2} \right) + \frac{1}{21} \cosh^2 \left( \frac{1}{2} \right)
 \end{aligned} \tag{14}$$

$$\begin{aligned}
 C_0 = \frac{1}{2} [\sinh(1) + 1] + 16 \cosh^2 \left( \frac{1}{2} \right) \\
 - 36 \sinh \left( \frac{1}{2} \right) \cosh \left( \frac{1}{2} \right) + \frac{1}{5} \cosh^2 \left( \frac{1}{2} \right)
 \end{aligned} \tag{15}$$

### 2.5 The general solution of governing equilibrium equations of the Beam

The general solution for transverse displacement  $w(x)$  and  $\phi(x)$  can be obtained from equation 8 and 9 by discarding the terms containing time (t) derivatives. Integrating and rearranging the equation 8, we obtained the following equation

$$\frac{d^3 w}{dx^3} = A_0 \frac{d^2 \phi}{dx^2} + \frac{Q(x)}{D} \tag{16}$$

Where,  $Q(x)$  is generalised shear force for beam.

$$Q(x) = \int_0^x q dx + k_1 \tag{17}$$

The second governing equation 9 can be written as:

$$\frac{d^3 w}{dx^3} = \frac{B_0}{A_0} \frac{d^2 \phi}{dx^2} - \beta \phi \tag{18}$$

Now using equations 16 and 18 a single equation in terms of  $\phi$  is obtained as:

$$\frac{d^2 \phi}{dx^2} - \lambda^2 \phi = \frac{Q(x)}{\alpha D} \tag{19}$$

$$\begin{aligned}
 w(x) = \left( \frac{x^5}{L^5} - \frac{10 x^3}{3 L^3} + \frac{7 x}{3 L} \right) + 10 \frac{E h^2 A_0^2}{G L^2 C_0} \times \\
 \left( \frac{\sinh \lambda x}{\lambda^2 L^2 \cosh \lambda L} - \frac{x}{L} \frac{1}{\lambda^2 L^2} - \frac{1 x^3}{6 L^3} + \frac{1 x}{6 L} \right)
 \end{aligned} \tag{25}$$

The general solution of equation 19 is as follows:

$$\phi = k_2 \cosh \lambda x + k_3 \sinh \lambda x - \frac{Q(x)}{\beta D} \quad (20)$$

Where the constants  $k_2$ ,  $k_3$ , and  $D$  used in above equations are given below:

$$\alpha = \left( \frac{B_0}{A_0} - A_0 \right) \quad \beta = \left( \frac{GAC_0}{DA_0} \right)$$

$$\lambda^2 = \frac{\beta}{\alpha} \quad D = EI$$

The equation of transverse displacement  $w(x)$  is obtained by substituting the expression of  $\phi(x)$  in equation 18 and integrating it thrice with respect to  $x$ . The general solution for  $w(x)$  is obtained as follows:

$$EIw(x) = \int \int \int \int q dx dx dx dx + \frac{D}{\lambda^3} \left( \frac{B_0}{A_0} \lambda^2 - \beta \right)$$

$$(k_2 \sinh \lambda x + k_3 \cosh \lambda x) \frac{k_1 x^3}{6} + k_4 \frac{x^2}{2} + k_5 x + k_6 \quad (21)$$

where  $k_1$ ,  $k_2$ ,  $k_3$ ,  $k_4$ ,  $k_5$  and  $k_6$  are the constants of integration and can be obtained by applying the boundary conditions of the beams.

### 3. Illustrative example:

In order to prove the efficiency of the present theory, the following numerical examples are considered. The following material properties for beam are used. Material properties:

1. Modulus of Elasticity  $E=210\text{GPa}$
2. Poissons ratio = 0.30
3. Density =7800 Kg/m<sup>3</sup>

3.1 Example 1: Simply supported beam with uniformly varying load  $q(x)=q_0(x/L)$

A simply supported beam with the origin of beam on left end support at  $x = 0$ . The beam is subjected to uniformly varying load of  $q(x)$  over the span  $L$  on surface  $z = h/2$  acting in the  $z$  direction given by

$$q(x) = q_0 \left( \frac{x}{L} \right)$$

The boundary conditions associated with this problem are as follows:

Simple supports:

The axial displacement, stresses and transverse shear stress

obtained based on above solutions are as follows

### 4. Numerical results:

The numerical results for axial displacement, transverse displacement, bending stress and transverse shear stress are presented in following non dimensional form and the values are presented in Table 1 and Table 2

$$\bar{w} = \frac{10Eb h^3}{q_0 L^4} \quad \bar{u} = \frac{Eb}{q_0 h} u$$

$$\phi(x) \quad \bar{\sigma}_x = \frac{b\sigma_x}{q_0} \quad \bar{\tau}_{zx} = \frac{b\tau_{zx}}{q_0}$$

$$\left( \frac{\cosh \lambda x}{\lambda L \cosh \lambda L} - \frac{1}{\lambda^2 L^2} - \frac{1}{2} \frac{x^2}{L^2} + \frac{1}{6} \right) \quad (26)$$

$$\bar{u} = -\frac{z}{h} \times \frac{1}{10} \times \frac{L^3}{h^3} \times \left( 5 \frac{x^4}{L^4} - 10 \frac{x^2}{L^2} + \frac{7}{3} \right)$$

$$- \frac{z}{h} \frac{E L A_0^2}{G h C_0} \left( \frac{\cosh \lambda x}{\lambda L \cosh \lambda L} - \frac{1}{\lambda^2 L^2} - \frac{1}{2} \frac{x^2}{L^2} + \frac{1}{6} \right)$$

$$+ \frac{A_0 E L}{C_0 G h} \times \left[ \sinh \left( \frac{z}{h} \right) - \frac{4}{3} \frac{z^3}{h^3} \cosh \left( \frac{1}{2} \right) \right]$$

$$\times \left( \frac{\cosh \lambda x}{\lambda L \cosh \lambda L} - \frac{1}{\lambda^2 L^2} - \frac{1}{2} \frac{x^2}{L^2} + \frac{1}{6} \right) \quad (27)$$

$$\bar{\sigma}_x = \left[ \left( \frac{20x^3}{L^3} - \frac{20x}{L} \right) + 10 \frac{E h^2 A_0^2}{G L^2 C_0} \left( \frac{\sinh \lambda x}{\cosh \lambda L} - \frac{x}{L} \right) \right] \times$$

$$\left( -\frac{z}{h} \times \frac{1}{10} \times \frac{L^2}{h^2} \right) + \frac{A_0}{C_0} \times \frac{E}{G} \left( \frac{\sinh \lambda x}{\cosh \lambda L} - \frac{x}{L} \right) \times$$

$$\left[ \sinh \left( \frac{z}{h} \right) - \frac{4}{3} \frac{z^3}{h^3} \cosh \left( \frac{1}{2} \right) \right] \quad (28)$$

$$\bar{\tau}_{zx}^{CR} = \frac{A_0 L}{C_0 h} \left[ \cosh \left( \frac{z}{h} \right) - \frac{4z^2}{h^2} \cosh \left( \frac{1}{2} \right) \right]$$

$$\left( \frac{\cosh \lambda x}{\cosh \lambda L} - \frac{1}{\lambda^2 L^2} - \frac{1}{2} \frac{x^2}{L^2} + \frac{1}{6} \right) \quad (29)$$

$$\bar{\tau}_{zx}^{EE} = \left[ \frac{60x^2}{L^2} - 20 + 10 \frac{E h^2 A_0^2}{G L^2 C_0} \left( \frac{\lambda L \cosh \lambda x}{\cosh \lambda L} - 1 \right) \right] \times$$

$$\left[ \frac{1}{80} \frac{L}{h} \left( \frac{4z^2}{h^2} - 1 \right) \right] + \frac{A_0 E h}{C_0 G L} \left( \frac{\lambda L \cosh \lambda x}{\cosh \lambda L} - 1 \right) \times$$

$$\left[ \frac{1}{48} \cosh \left( \frac{1}{2} \right) \left( \frac{16z^4}{h^4} - 1 \right) - \cosh \left( \frac{z}{h} \right) + \cosh \left( \frac{1}{2} \right) \right] \quad (30)$$

Table1: Non-Dimensional Axial Displacement ( $u$ ) at ( $x=0.75L, z=h/2$ ), Transverse Deflection ( $w$ ) at ( $x=0.75L, z=0.0$ ), Axial stress ( $\sigma_x$ ) at ( $x=0.75L, z=h/2$ ), Maximum Transverse shear stresses ( $\tau_{zx}$ ) and ( $\tau_{zx}$ ) at ( $x=0.0, z=0.0$ ) of simply supported beam subjected to Varying load for Aspect Ratio 4

Source	Model	$\bar{u}$	$\bar{w}$	$\bar{\sigma}_x$	$\bar{\tau}_{zx}^{CR}$	$\bar{\tau}_{zx}^{EE}$
Present	HPSDT	0.6874	-5.5903	-5.4451	-0.9992	0.9959
Dahake	TSDT	0.6891	-5.6081	-5.4438	-1.0320	0.9968
Krishna Murty	HSDT	0.6874	-5.5902	-5.4450	-0.9988	0.9959
Timoshenko	FSDT	0.6877	-5.4807	-5.2500	-0.1436	1.0000
Bernoulli-Euler	ETB	0.5811	-5.4708	-5.2500	-	1.0000

Table2:

Non-Dimensional Axial Displacement ( $u$ ) at ( $x=0.75L, z=h/2$ ), Transverse Deflection ( $w$ ) at ( $x=0.75L, z=0.0$ ), Axial stress ( $\sigma_x$ ) at ( $x=0.75L, z=h/2$ ), Maximum Transverse shear stresses ( $\tau_{zx}$ ) and ( $\tau_{zx}$ ) at ( $x=0.0, z=0.0$ ) of simply supported beam subjected to Varying load for Aspect Ratio 10

Source	Model	$\bar{u}$	$\bar{w}$	$\bar{\sigma}_x$	$\bar{\tau}_{zx}^{CR}$	$\bar{\tau}_{zx}^{EE}$
Present	HPSDT	0.5981	-85.7800	-33.0076	-2.5005	2.4984
Dahake	TSDT	0.5983	-85.8249	-33.0371	-2.5801	2.4987
Krishna Murty	HSDT	0.5981	-85.7798	-33.0075	-2.4995	2.4984
Timoshenko	FSDT	0.5981	-85.4818	-32.8125	-0.8974	2.5000
Bernoulli-Euler	ETB	0.5811	-85.4818	-32.8125	-	2.5000

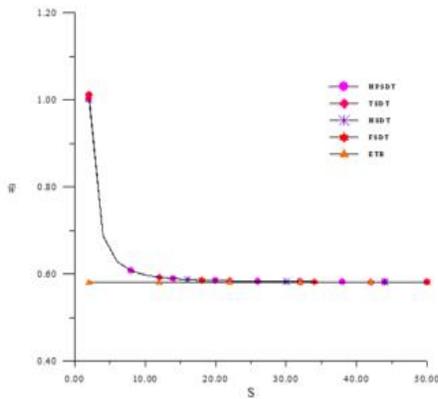


Figure 2: Variation of Transverse Displacement  $\bar{w}$

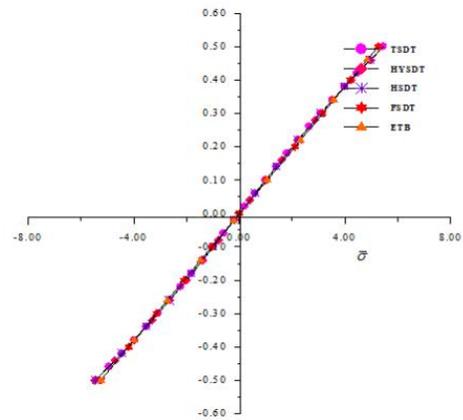


Figure 3: Variation of Maximum Axial displacement ( $u$ ) for AS 04

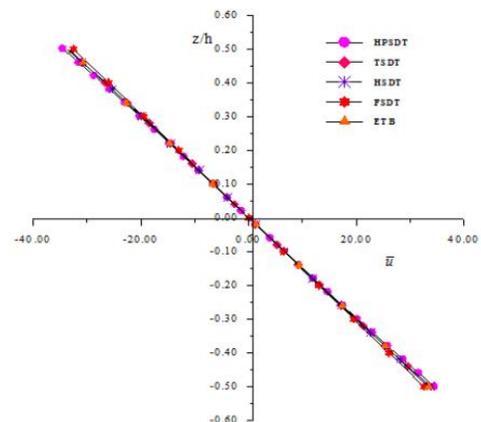


Figure 4: Variation of Maximum Axial displacement ( $u$ ) for AS 10

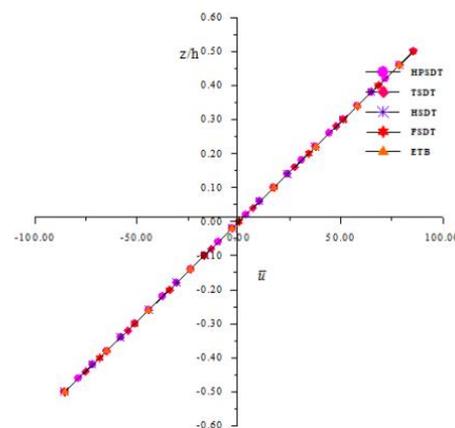


Figure 5: Variation of Maximum Axial stress ( $\sigma_x$ ) for AS 04

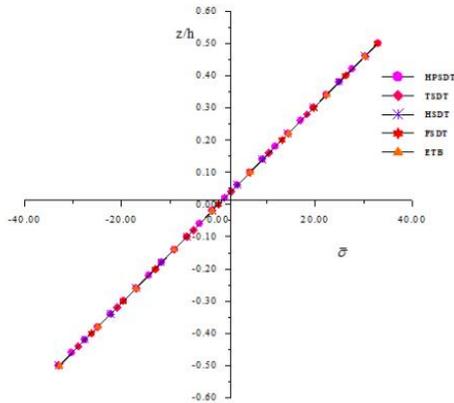


Figure 6: Variation of Maximum Axial stress (  $\sigma$  ) for AS 10

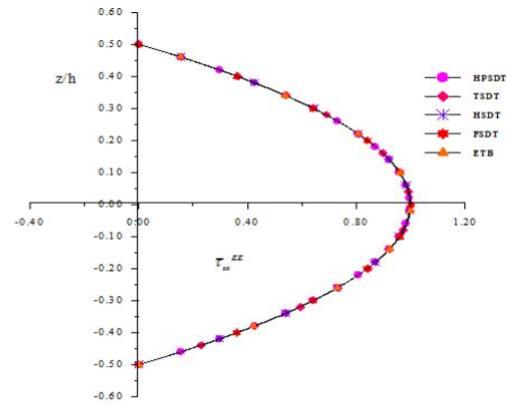


Figure 9: Variation of Transverse shear stress(  $\tau_{xx}$  ) for AS 04

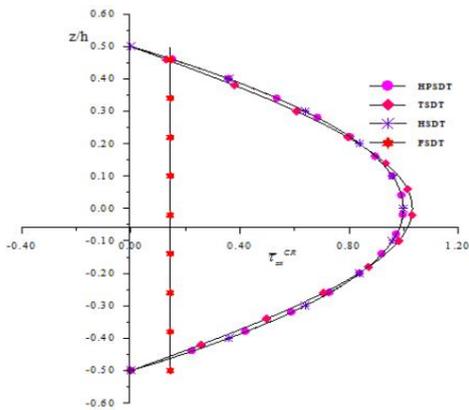


Figure 7: Variation of Transverse shear stress (  $\tau_{xz}$  ) for AS 04

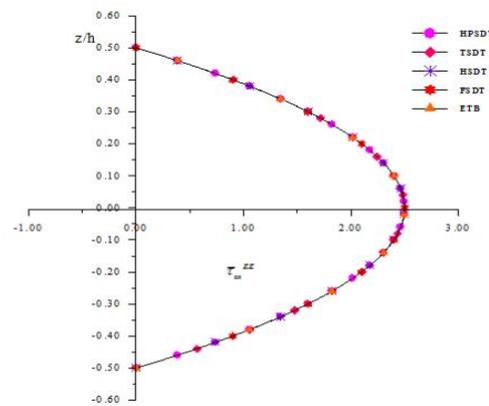


Figure 10: Variation of Transverse shear stress(  $\tau_{xx}$  ) for AS 10

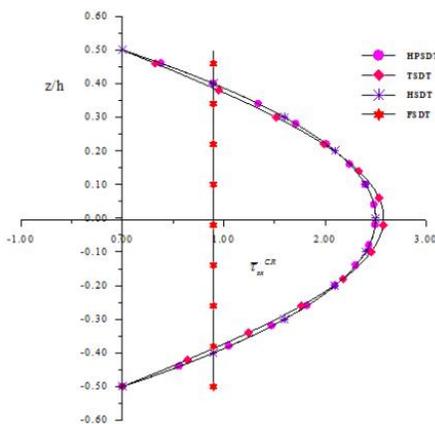


Figure 8: Variation of Transverse shear stress (  $\tau_{xz}$  ) for AS 10

### 5. Concluding remark:

From the static flexural analysis of simply supports beam following conclusion are drawn:

1. The result of maximum transverse displacement obtained by present theory is in excellent agreement with those of other equivalent refined and higher order theories. The variation of  $w$  for AS 4 and 10 are presented as shown in Figure 2.
2. From Figure 3 and Figure 4, it can be observed that, the result of axial displacement for beam subjected to varying load varies linearly through the thickness of beam for AS 4 and 10 respectively.
3. The maximum non dimensional axial stresses  $\sigma$  for AS 4 and 10 varies linearly through the thickness of beam as shown in Figure 5 and Figure 6 respectively.
4. The transverse shear stress is obtained directly by constitutive relation. Figure 7, 8, 9 and Figure 10 shows the through thickness variation of transverse shear stress for thick isotropic beam for AS 4 and 10. From this it can be observed that, the transverse shear stress satisfy the zero condition at top ( $z=h/2$ ) and at bottom ( $z=-h/2$ ) surface of the beam.

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